

A New Factorization of an Order- p Tensor as a Product of Order- p Tensors

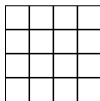
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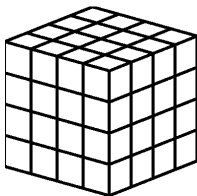
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What are Tensors?

- Second-order tensor $A = (a_{ij}) \in \mathbb{R}^{n_1 \times n_2}$



- Third-order tensor $\mathcal{A} = (a_{ijk}) \in \mathbb{R}^{n_1 \times n_2 \times n_3}$



- p^{th} -order tensor $\mathcal{A} = (a_{i_1 i_2 \dots i_p}) \in \mathbb{R}^{n_1 \times \dots \times n_p}$

Motivation: A two-way decomposition

Suppose $U \in \mathbb{R}^{M \times M}$, $V \in \mathbb{R}^{N \times N}$ are orthogonal, and $\Sigma = U^T A V$, then

$$\begin{aligned} A = U \Sigma V^T &= \sum_{i=1}^M \sum_{j=1}^N \sigma_{ij} u_i v_j^T \\ &= \sum_{i=1}^M \sum_{j=1}^N \sigma_{ij} (u_i \circ v_j) \end{aligned}$$

where $u_i = U(:, i)$, $v_j = V(:, j)$

Tensor Decompositions

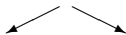
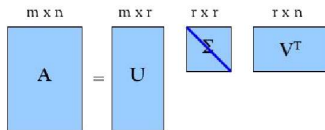
Let $\mathcal{A} \in \mathbb{R}^{M \times N \times P}$

Goal: To find $U \in \mathbb{R}^{M \times M}$, $V \in \mathbb{R}^{N \times N}$, $W \in \mathbb{R}^{P \times P}$, and $\Sigma = (\sigma_{ijk}) \in \mathbb{R}^{M \times N \times P}$ such that

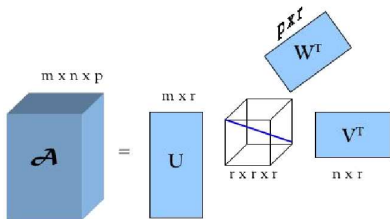
$$\mathcal{A} = \sum_{i=1}^M \sum_{j=1}^N \sum_{k=1}^P \sigma_{ijk} (u_i \circ v_j \circ w_k)$$

where $u_i = U(:, i)$, $v_j = V(:, j)$, $w_k = W(:, k)$

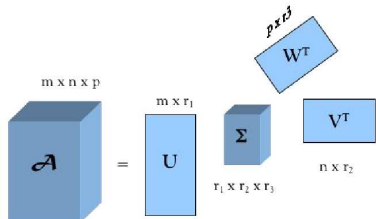
Orthogonal or Diagonal for Tensors



Case 1:
Diagonal Σ



Case 2:
Orthogonal U, V, W



What other factorizations are possible?

- Develop different notions of factorizations and projections based on different tensor operations
- Tie factorizations to fundamental concepts in linear algebra such as group structure, invertibility, existence, uniqueness
- New compression strategies that may be modified for tensors with special structure
- Investigate computational efficiencies with regard to sparse and dense tensors

Tensor-tensor Multiplication (contracted product)

Contracted product in the *first-mode*:

$$\begin{aligned} \mathcal{A} &\in \mathbb{R}^{L \times M_1 \times N_1} \\ \mathcal{B} &\in \mathbb{R}^{L \times M_2 \times N_2} \end{aligned} \quad \Rightarrow \quad \mathcal{AB} \in \mathbb{R}^{M_1 \times N_1 \times M_2 \times N_2}$$

$$(\mathcal{AB})_{m_1 n_1 m_2 n_2} = \sum_{\ell=1}^L \mathcal{A}_{\ell m_1 n_1} \mathcal{B}_{\ell m_2 n_2}$$

$$m_1 = 1, \dots, M_1$$

$$m_2 = 1, \dots, M_2$$

$$n_1 = 1, \dots, N_1$$

$$n_2 = 1, \dots, N_2$$

Tensor-tensor Multiplication

Using contracted product...

- Set of all third-order tensors is not closed
- No notion of inverse possible

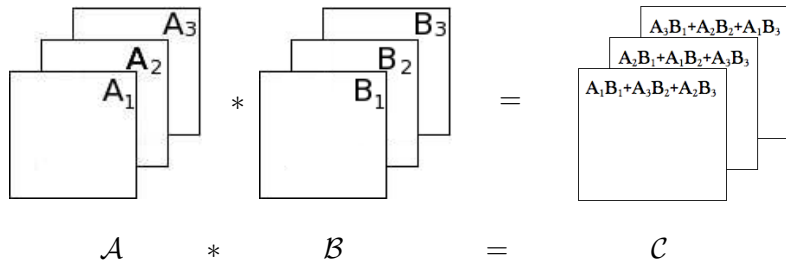
What happens if we create an operation that is closed under “multiplication”?

New tensor-tensor operation

$$\begin{aligned} \mathcal{A} &\in \mathbb{R}^{L \times M \times N} \\ \mathcal{B} &\in \mathbb{R}^{M \times P \times N} \end{aligned} \quad \Rightarrow \quad \mathcal{A} * \mathcal{B} \in \mathbb{R}^{L \times P \times N}$$

- Operation defined in terms of the tensor “slices”
- Circulant matrices play a role
- Operation is associative
- Can define an inverse
- Set of $N \times N \times N$ invertible tensors form a group under this operation

New tensor-tensor operation



$$\begin{bmatrix} A_1 & A_3 & A_2 \\ A_2 & A_1 & A_3 \\ A_3 & A_2 & A_1 \end{bmatrix} \begin{bmatrix} B_1 \\ B_2 \\ B_3 \end{bmatrix} = \begin{bmatrix} A_1 B_1 + A_3 B_2 + A_2 B_3 \\ A_2 B_1 + A_1 B_2 + A_3 B_3 \\ A_3 B_1 + A_2 B_2 + A_1 B_3 \end{bmatrix} = \begin{bmatrix} C(:, :, 1) \\ C(:, :, 2) \\ C(:, :, 3) \end{bmatrix}$$

Computation

More efficient if performed in the Fourier domain.

For example, if $\mathcal{A} \in \mathbb{R}^{L \times M \times 4}$, $\mathcal{B} \in \mathbb{R}^{M \times P \times 4}$:

$$\begin{aligned} \mathcal{C} &= \mathcal{A} * \mathcal{B} \\ &= (F_4^* \otimes I_L)(F_4 \otimes I_L) \begin{bmatrix} A_1 & A_4 & A_3 & A_2 \\ A_2 & A_1 & A_4 & A_3 \\ A_3 & A_2 & A_1 & A_4 \\ A_4 & A_3 & A_2 & A_1 \end{bmatrix} (F_4^* \otimes I_M)(F_4 \otimes I_M) \begin{bmatrix} B_1 \\ B_2 \\ B_3 \\ B_4 \end{bmatrix} \\ &= (F_4^* \otimes I_L) \begin{bmatrix} D_1 & & & \\ & D_2 & & \\ & & D_3 & \\ & & & D_4 \end{bmatrix} \begin{bmatrix} \tilde{B}_1 \\ \tilde{B}_2 \\ \tilde{B}_3 \\ \tilde{B}_4 \end{bmatrix} \end{aligned}$$

Higher Order Tensor Operations (recursive)

Suppose $\mathcal{A}, \mathcal{B} \in \mathbb{R}^{3 \times 3 \times 3 \times 3}$ ($A_{ij} \in \mathbb{R}^{3 \times 3}$)

$$\mathcal{A}_1 = \mathcal{A}(:, :, :, 1) = \begin{array}{c} \text{A}_{31} \\ \text{A}_{21} \\ \text{A}_{11} \end{array}$$

$$\mathcal{A}_2 = \mathcal{A}(:, :, :, 2) = \begin{array}{c} \text{A}_{32} \\ \text{A}_{22} \\ \text{A}_{12} \end{array}$$

$$\mathcal{A}_3 = \mathcal{A}(:, :, :, 3) = \begin{array}{c} \text{A}_{33} \\ \text{A}_{23} \\ \text{A}_{13} \end{array}$$

$$\mathcal{B}_1 = \mathcal{B}(:, :, :, 1) = \begin{array}{c} \text{B}_{31} \\ \text{B}_{21} \\ \text{B}_{11} \end{array}$$

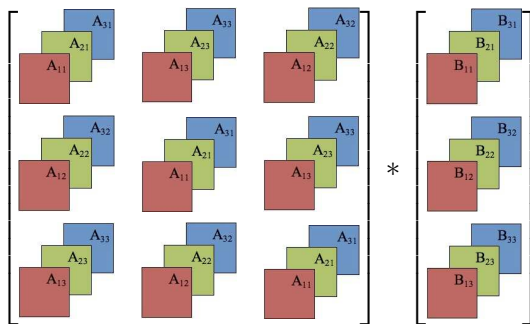
$$\mathcal{B}_2 = \mathcal{B}(:, :, :, 2) = \begin{array}{c} \text{B}_{32} \\ \text{B}_{22} \\ \text{B}_{12} \end{array}$$

$$\mathcal{B}_3 = \mathcal{B}(:, :, :, 3) = \begin{array}{c} \text{B}_{33} \\ \text{B}_{23} \\ \text{B}_{13} \end{array}$$

Higher Order Tensor Operations (recursive)

Then, $\mathcal{A} * \mathcal{B}$:

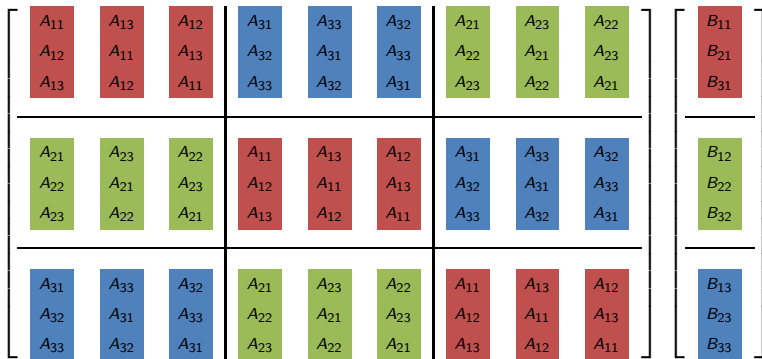
$$\begin{bmatrix} \mathcal{A}_1 & \mathcal{A}_3 & \mathcal{A}_2 \\ \mathcal{A}_2 & \mathcal{A}_1 & \mathcal{A}_3 \\ \mathcal{A}_3 & \mathcal{A}_2 & \mathcal{A}_1 \end{bmatrix} * \begin{bmatrix} \mathcal{B}_1 \\ \mathcal{B}_2 \\ \mathcal{B}_3 \end{bmatrix}$$



9x9x3

9x3x3

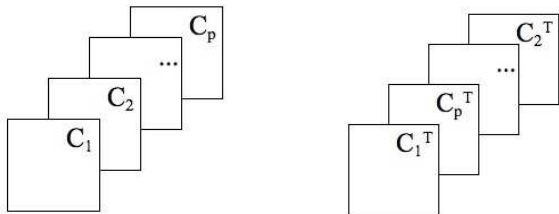
Higher Order Tensor Operations (recursive)



Matrix multiply \rightarrow Leads to a recursive algorithm

Transpose

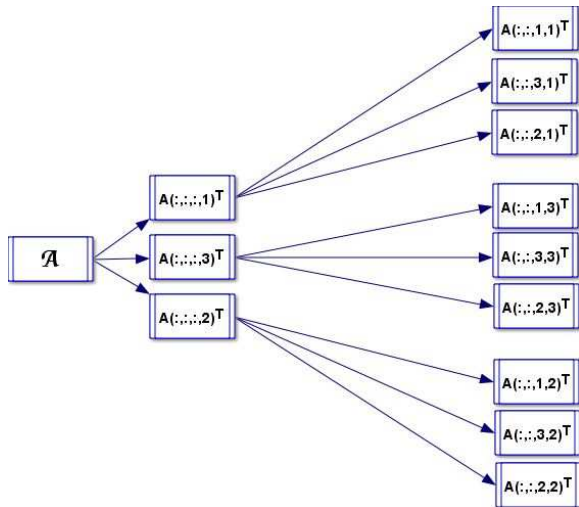
Let $\mathcal{C} \in \mathbb{R}^{L \times M \times P}$ with faces $C_1, \dots, C_P \in \mathbb{R}^{L \times M}$. Then



It follows that $(\mathcal{B} * \mathcal{C})^T = \mathcal{C}^T * \mathcal{B}^T$

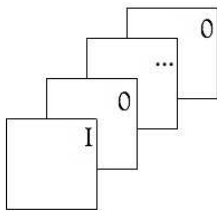
Higher Order Tensor Transpose (recursive)

The higher order tensor transpose follows a recursive process.



Identity

The $N \times N \times P$ **identity tensor**, \mathcal{I} , is the tensor whose frontal face is the $N \times N$ identity matrix and whose other faces are zeros.



In general, $\mathcal{A} * \mathcal{I} = \mathcal{I} * \mathcal{A} = \mathcal{A}$

Inverse

Let $\mathcal{A} \in \mathbb{R}^{N \times N \times N}$. Then the **tensor inverse** of \mathcal{A} is any tensor $\mathcal{B} \in \mathbb{R}^{N \times N \times N}$ such that

$$\mathcal{A} * \mathcal{B} = \mathcal{B} * \mathcal{A} = \mathcal{I}$$

We denote the inverse of \mathcal{A} as \mathcal{A}^{-1} .

It follows that $(\mathcal{A} * \mathcal{B})^{-1} = \mathcal{B}^{-1} * \mathcal{A}^{-1}$

Frobenius Norm and Orthogonality

Let $\mathcal{A} = (a_{ijk}) \in \mathbb{R}^{L \times M \times N}$. Then the **Frobenius norm** of \mathcal{A} is

$$\|\mathcal{A}\|_F = \sqrt{\sum_{i=1}^L \sum_{j=1}^M \sum_{k=1}^N a_{ijk}^2}$$

Let $Q \in \mathbb{R}^{N \times N \times P}$. Q is **orthogonal** if

$$Q^T * Q = Q * Q^T = \mathcal{I}$$

If \mathcal{A} is a tensor, then it follows that

$$\|Q * \mathcal{A}\|_F = \|\mathcal{A}\|_F$$

Tensor SVD

Let $\mathcal{A} \in \mathbb{R}^{L \times M \times N}$. Then \mathcal{A} can be factored as

$$\mathcal{A} = \mathcal{U} * \mathcal{S} * \mathcal{V}^T$$

where $\mathcal{U} \in \mathbb{R}^{L \times L \times N}$ and $\mathcal{V} \in \mathbb{R}^{M \times M \times N}$ are orthogonal tensors and $\mathcal{S} \in \mathbb{R}^{L \times M \times N}$ has diagonal matrix faces.

If $\mathcal{A} \in \mathbb{R}^{N \times N \times N}$,

$$\mathcal{A} = \sum_{i=1}^N \mathcal{U}(:, i, :) * \mathcal{S}(i, i, :) * \mathcal{V}(:, i, :)^T$$

Tensor SVD: computation

$$A = U * S * V^T$$

- Computation of the tensor SVD involves SVDs of block diagonal elements obtained from block diagonalizing the circulant matrix generated by \mathcal{A}
- Using the SVDs of the blocks leads to algorithms for compression
- Decomposition extends recursively to order- p tensors when $p > 3$

Tensor SVD: computation

$$\begin{bmatrix} A_1 & A_4 & A_3 & A_2 \\ A_2 & A_1 & A_4 & A_3 \\ A_3 & A_2 & A_1 & A_4 \\ A_4 & A_3 & A_2 & A_1 \end{bmatrix} = (F \otimes I) \begin{bmatrix} D_1 & & & \\ & D_2 & & \\ & & D_3 & \\ & & & D_4 \end{bmatrix} (F^* \otimes I)$$

$$= (F \otimes I) \begin{bmatrix} U_1 \Sigma_1 V_1^T & & & \\ & U_2 \Sigma_2 V_2^T & & \\ & & U_3 \Sigma_3 V_3^T & \\ & & & U_4 \Sigma_4 V_4^T \end{bmatrix} (F^* \otimes I)$$

$$= (F \otimes I) \begin{bmatrix} U_1 & & & \\ & U_2 & & \\ & & U_3 & \\ & & & U_4 \end{bmatrix} \begin{bmatrix} \Sigma_1 & & & \\ & \Sigma_2 & & \\ & & \Sigma_3 & \\ & & & \Sigma_4 \end{bmatrix} \begin{bmatrix} V_1^T & & & \\ & V_2^T & & \\ & & V_3^T & \\ & & & V_4^T \end{bmatrix} (F^* \otimes I)$$

Compression Strategy

Suppose $\mathcal{A} \in \mathbb{R}^{L \times M \times N}$

Can prove that if $\mathcal{A} = \mathcal{U} * \mathcal{S} * \mathcal{V}^T$ then

$$\sum_{i=1}^N \mathcal{U}(:, :, i), \quad \sum_{i=1}^N \mathcal{V}(:, :, i) \quad \text{are orthogonal.}$$

Therefore

$$\sum_{i=1}^N \mathcal{A}(:, :, i) = \left(\sum_{i=1}^N \mathcal{U}(:, :, i) \right) \left(\sum_{i=1}^N \mathcal{S}(:, :, i) \right) \left(\sum_{i=1}^N \mathcal{V}(:, :, i) \right)^T$$

Compression Strategy

$$\sum_{i=1}^N \mathcal{A}(:, :, i) = \left(\sum_{i=1}^N \mathcal{U}(:, :, i) \right) \left(\sum_{i=1}^N \mathcal{S}(:, :, i) \right) \left(\sum_{i=1}^N \mathcal{V}(:, :, i) \right)^T$$

- Choose $k_1 \ll L$, $k_2 \ll M$ and compute truncated SVD, $\tilde{U}\tilde{S}\tilde{V}^T$
- Set $\mathcal{T}(:, :, i) = \tilde{U}^T \mathcal{A}(:, :, i) \tilde{V}$ for $i = 1, \dots, N$
- Can rewrite “compressed” tensor \mathcal{A}_c as sum of outer products:

$$\mathcal{A} \approx \mathcal{A}_c = \sum_{i=1}^{k_1} \sum_{j=1}^{k_2} \tilde{U}(:, i) \circ \tilde{V}(:, j) \circ \mathcal{T}(i, j, :)$$

- Computationally, do *not* need to compute Tensor SVD to obtain representation above

New Tensor SVD Factorization

Advantages:

- Orientation Specific
- Allows for weighting of the tensor slices according to data
- Emits a factorization with an underlying group structure that easily extends other matrix factorizations to tensors
- Randomly generated tensors, compression (measured in norm) is similar to existing factorizations

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Weighting

Suppose \mathcal{A} is an $L \times M \times N$ tensor

Standard Compression Strategy:

$$A = \sum_{i=1}^N \mathcal{A}(:, :, i)$$

Weighted Compression Strategy:

$$A = \sum_{i=1}^N w(i) \mathcal{A}(:, :, i)$$

where w is a weighting vector

Used when there is a known dependence on the tensor slices

QR and Eigenvalue Extensions

Suppose $\mathcal{A} \in \mathbb{R}^{N \times N \times N}$. Then \mathcal{A} can be factored as


$$\mathcal{A} = \mathcal{Q} * \mathcal{R}$$

\mathcal{Q} orthogonal, \mathcal{R} with upper triangular faces

$$\mathcal{A} = \mathcal{Q} * \mathcal{B} * \mathcal{Q}^T$$

\mathcal{Q} orthogonal, \mathcal{B} with upper triangular faces

Summary

- New definitions allow for greater flexibility in design of compression algorithms for tensors
- Can be extended to other matrix factorizations (e.g., QR)
- Computationally efficient
- Allows for weighting of tensor faces
- Underlying algebraic structure within the factorization

Thank you!